

Throttling Automatic Vectorization: When Less is More

Vasileios Porpodas and Timothy M. Jones

University of Cambridge

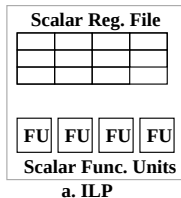
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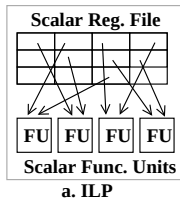
Why SIMD Vectorization?

- Scalable parallelism



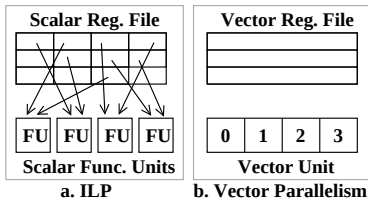
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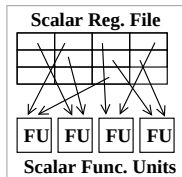
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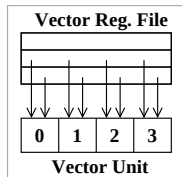


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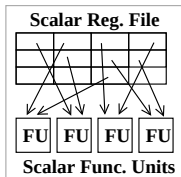
a. ILP



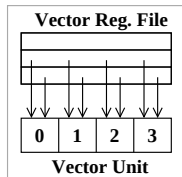
b. Vector Parallelism

Why SIMD Vectorization?

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- High Performance



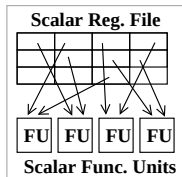
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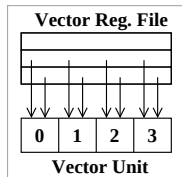
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- Energy efficiency



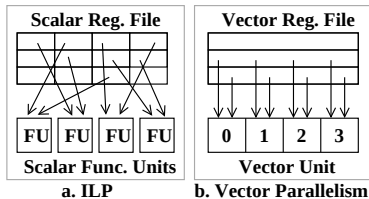
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b. Vector Parallelism

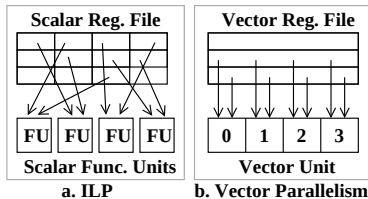
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- Supported since mid 90's
- Frequent updates of vector ISAs



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- Scalable parallelism
- High Performance
- Energy efficiency
- Supported since mid 90's
- Frequent updates of vector ISAs
- Vector generation not done in hardware
- Low-level programming or capable compiler



SLP Straight-Line Code Vectorizer

- Superword Level Parallelism [Larsen PLDI'00]

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 - Unroll loop and vectorize with SLP
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- In theory it should be a superset of loop-vectorizer
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 - Even if loop-vectorizer fails, SLP could partly succeed
- In practice it is missing features present in the Loop vectorizer (Interleaved Loads, Predication)

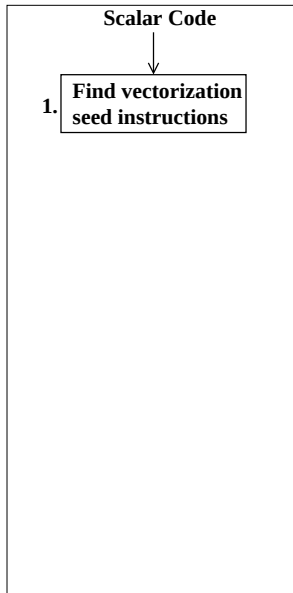
SLP Vectorization Algorithm

- Input is scalar IR

Scalar Code

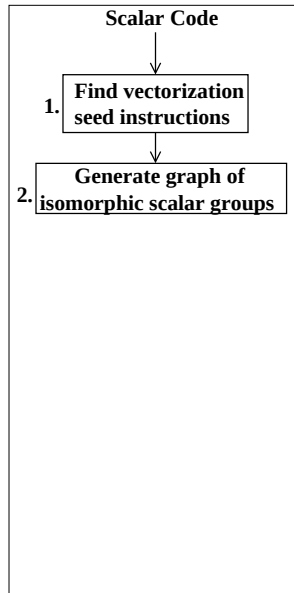
SLP Vectorization Algorithm

- Input is scalar IR
- Seed instructions are:
 - ① Consecutive Stores
 - ② Reductions



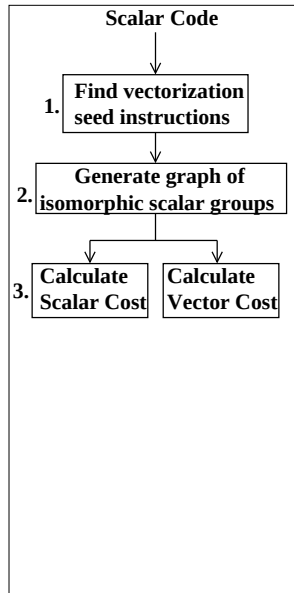
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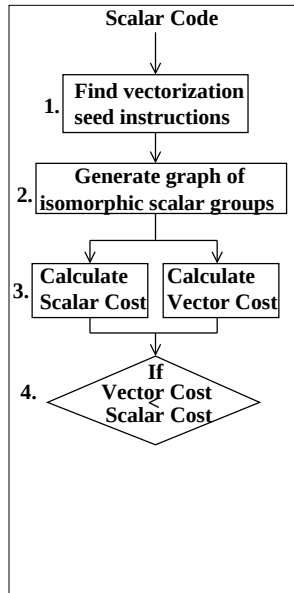
SLP Vectorization Algorithm

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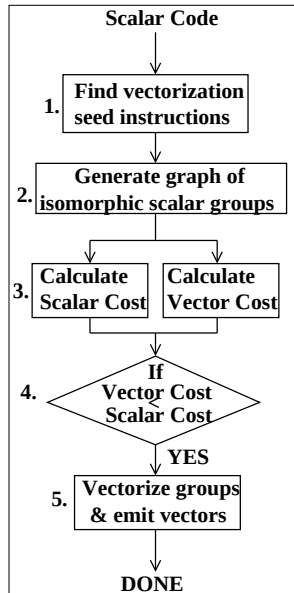
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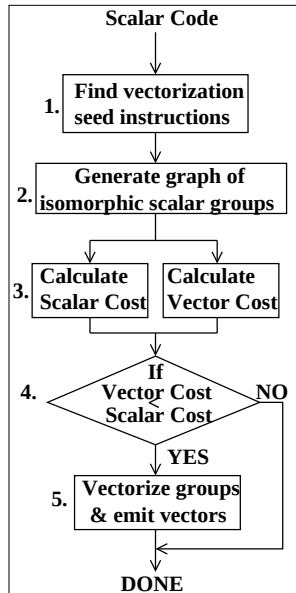
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When SLP is not profitable

- Costs outweigh the benefits: E.g. too many gather/scatter instructions

Original	Vectorized
ADD1	
ADD2	
ADD3	
ADD4	

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Original	Vectorized				
ADD1	<table><tr><td>ADD1</td><td>ADD2</td><td>ADD3</td><td>ADD4</td></tr></table>	ADD1	ADD2	ADD3	ADD4
ADD1		ADD2	ADD3	ADD4	
ADD2					
ADD3					
ADD4					

When SLP is not profitable

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Original	Vectorized				
ADD1	Insert1				
ADD2	Insert2				
ADD3	Insert3				
ADD4	Insert4				
	<table><tr><td>ADD1</td><td>ADD2</td><td>ADD3</td><td>ADD4</td></tr></table>	ADD1	ADD2	ADD3	ADD4
ADD1	ADD2	ADD3	ADD4		
	Extract1				
	Extract2				
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SLP not profitable for whole graph

```
A[i]  =B[i]    + (C[2*i]*(D[2*i]+(E[2*i]*C[2*i])))  
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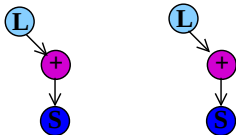
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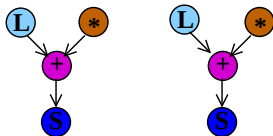
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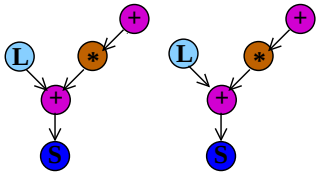
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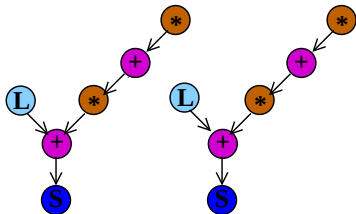
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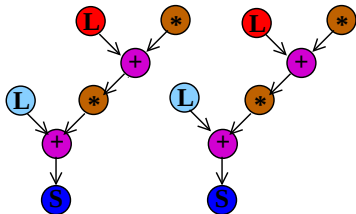
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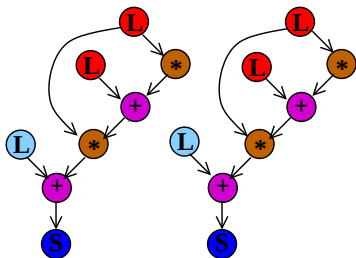
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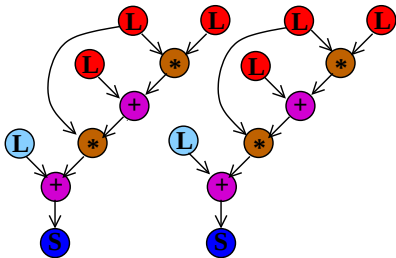
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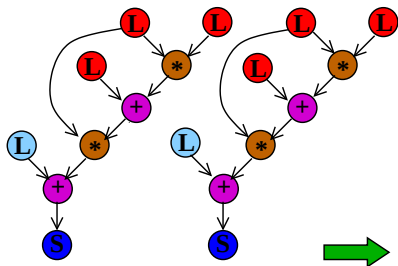
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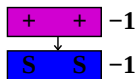
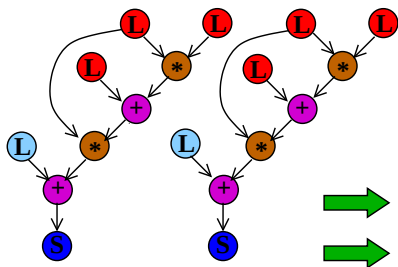


S S -1

Total Cost: -1

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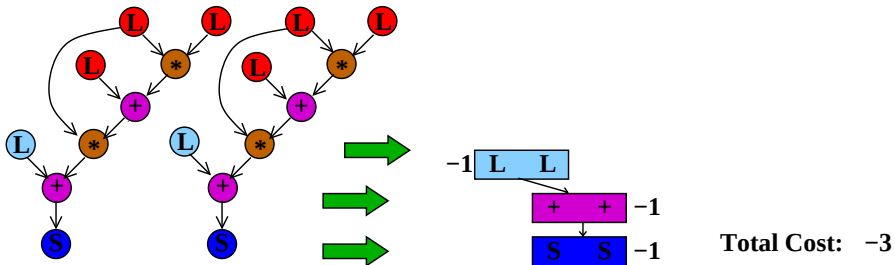
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Total Cost: -2

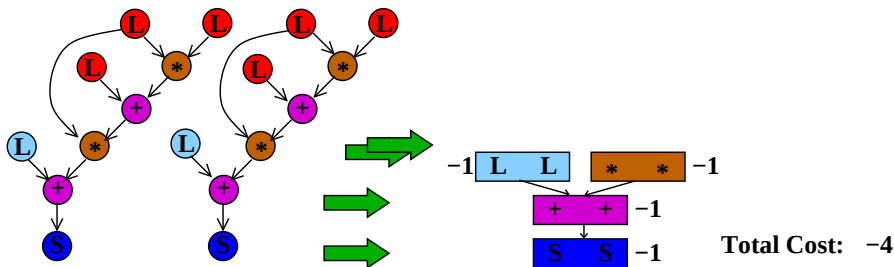
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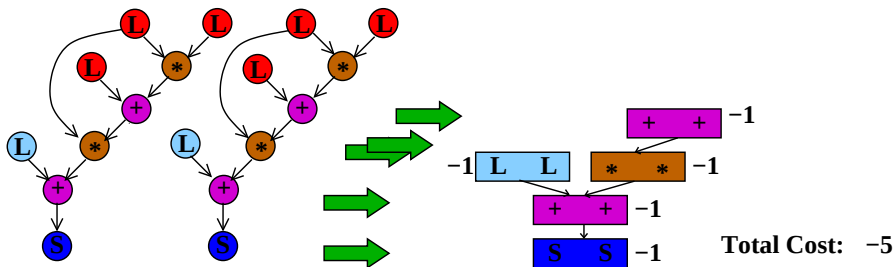
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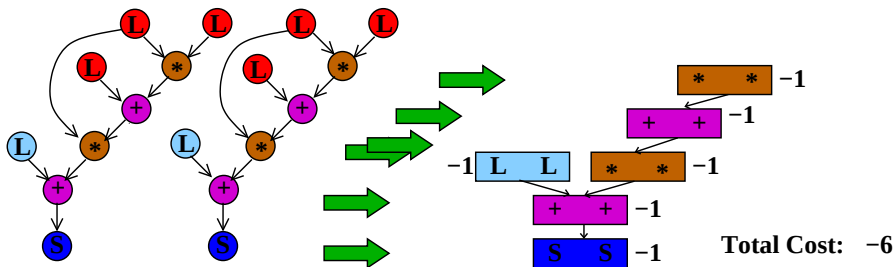
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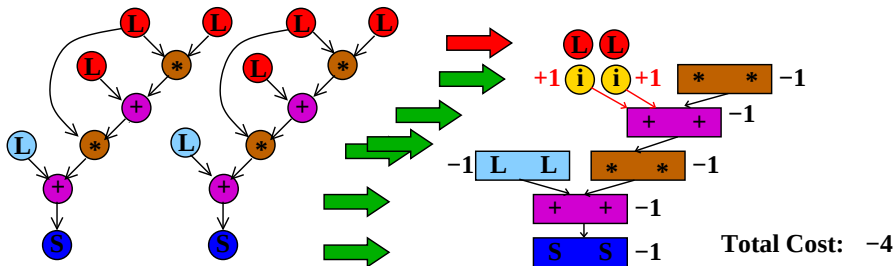
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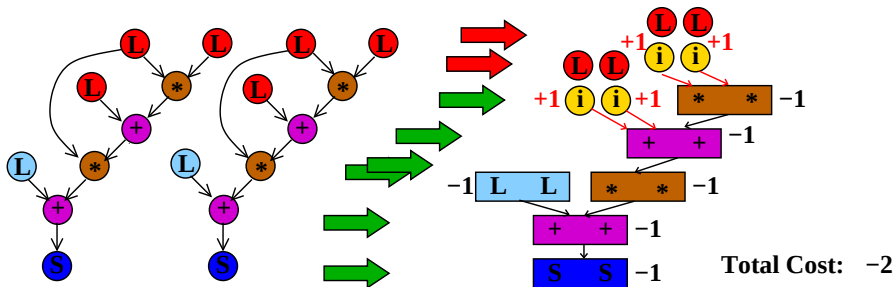
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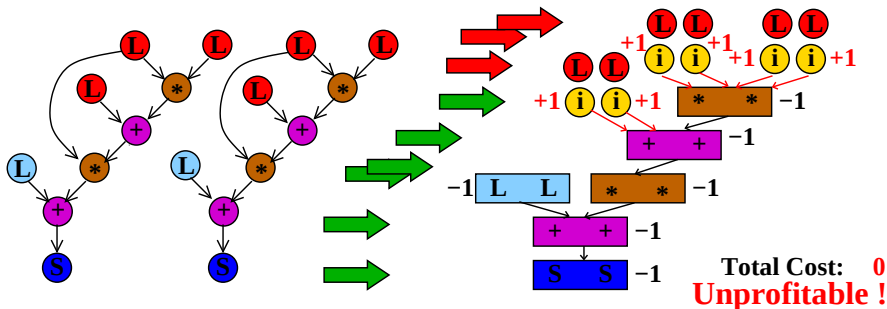
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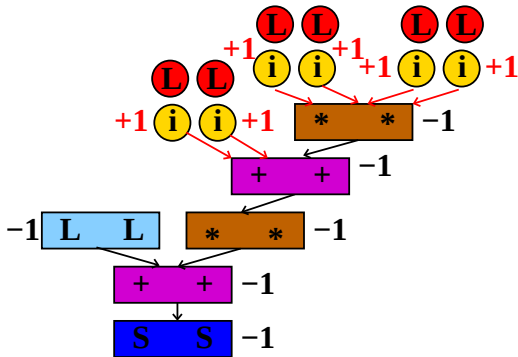
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TSLP removes unprofitable region

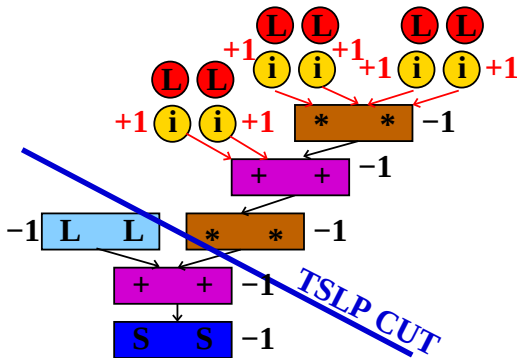
SLP



Total Cost: 0
Unprofitable!

TSLP removes unprofitable region

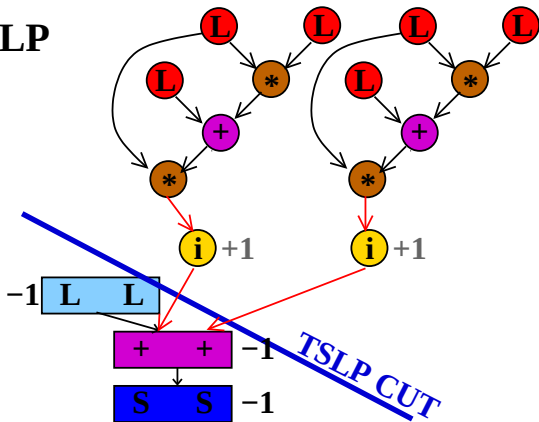
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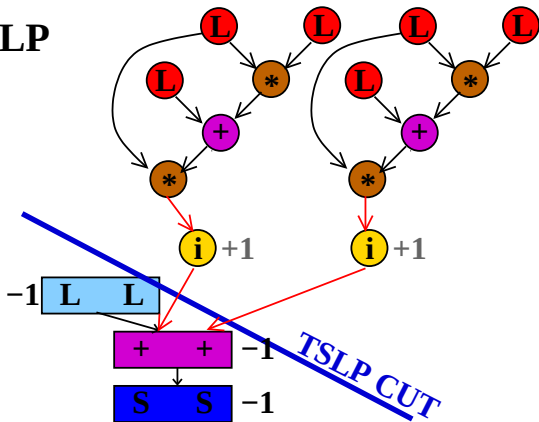
TSLP



Total Cost:

TSLP removes unprofitable region

TSLP



Total Cost: -1
Profitable !

TSLP Algorithm

- Extension to SLP

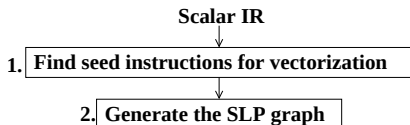
Scalar IR



1. Find seed instructions for vectorization

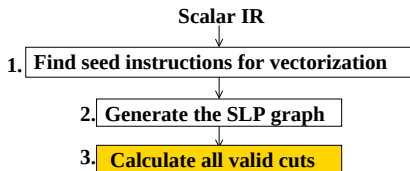
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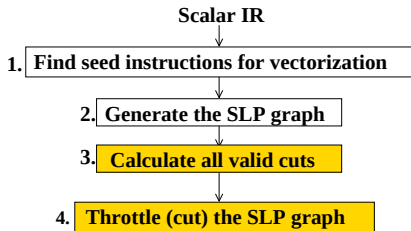
TSLP Algorithm

- Extension to SLP
- Try out many cuts



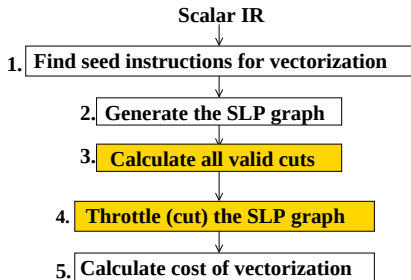
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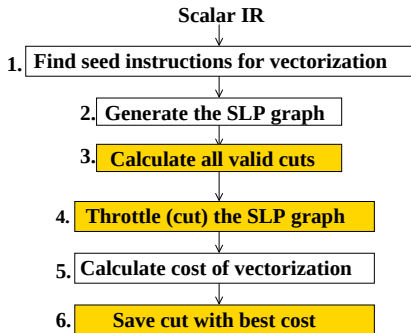
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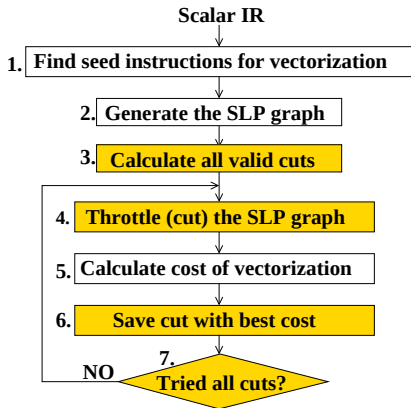
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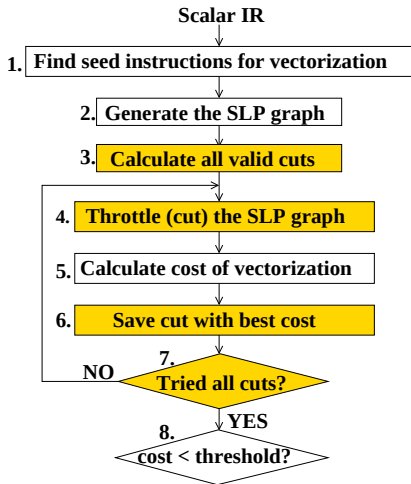
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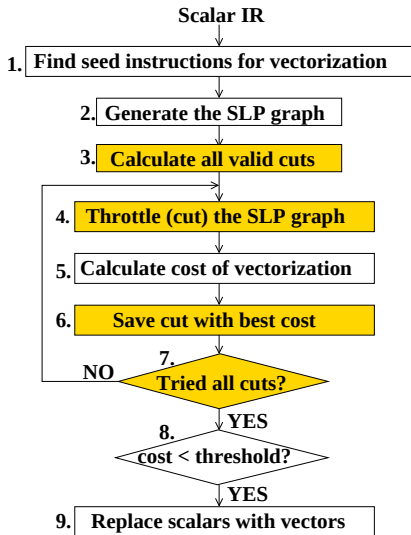
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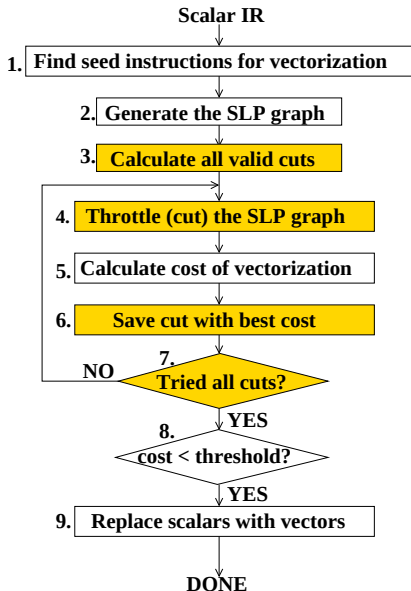
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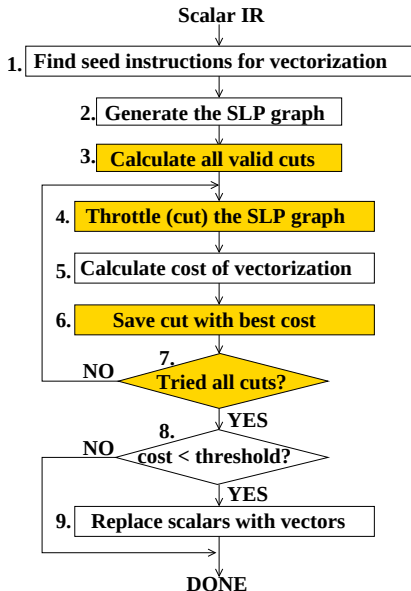
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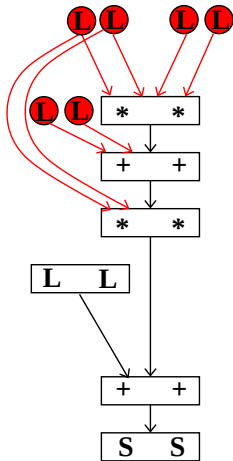


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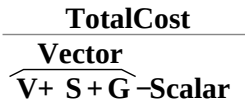
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- Vanilla SLP



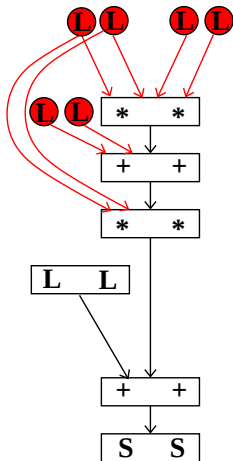
Cost calculation example



TotalCost

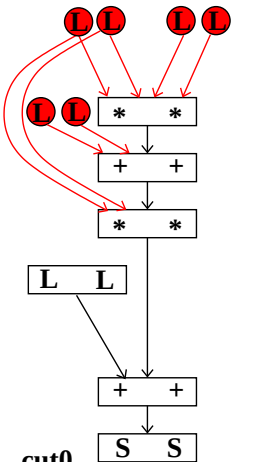


Cost calculation example



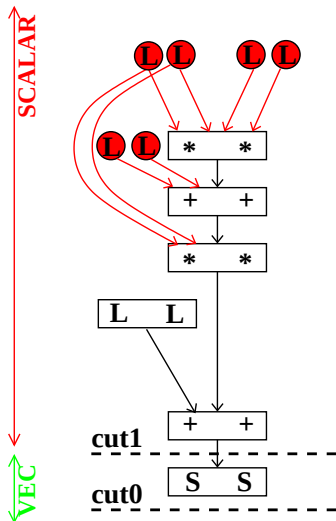
TotalCost	
Vector	
V+	S+G-Scalar
- 18	
- 18	
- 18	
- 18	
- 18	
- 18	
- 18	
- 18	

Cost calculation example



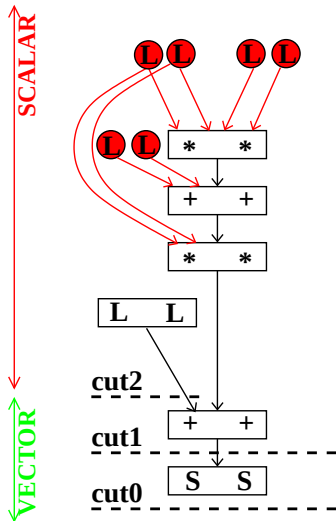
TotalCost	
Vector	
$\widehat{V + S + G}$ -Scalar	
- 18	
- 18	
- 18	
- 18	
- 18	
- 18	
- 18	
$0 + 18 + 0 - 18 = 0$	

Cost calculation example



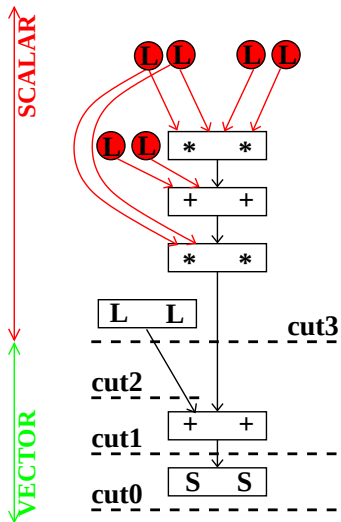
TotalCost	
Vector	
$V + S + G$	Scalar
- 18	
- 18	
- 18	
- 18	
- 18	
- 18	
$1 + 16 + 2 - 18$	$= +1$
$0 + 18 + 0 - 18$	$= 0$

Cost calculation example



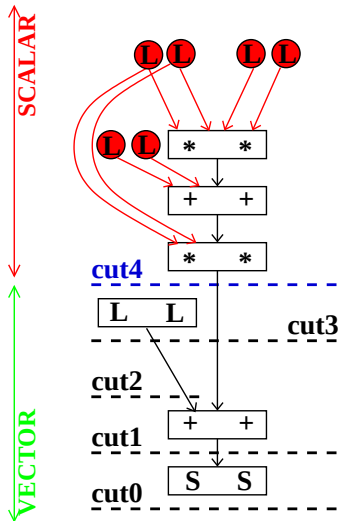
TotalCost	
Vector	
$V + S + G$	Scalar
- 18	
- 18	
- 18	
- 18	
- 18	
$5 + 8 + 8 - 18$	= +3
$1 + 16 + 2 - 18$	= +1
$0 + 18 + 0 - 18$	= 0

Cost calculation example



TotalCost	
Vector	
$V + S + G - \text{Scalar}$	
- 18	
- 18	
- 18	
- 18	
$2 + 14 + 4 - 18 =$	+2
$5 + 8 + 8 - 18 =$	+3
$1 + 16 + 2 - 18 =$	+1
$0 + 18 + 0 - 18 =$	0

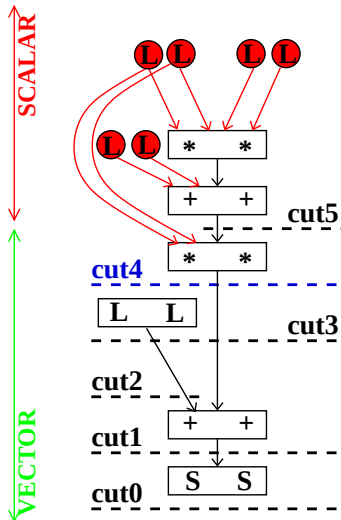
Cost calculation example



TotalCost	
Vector	
V+ S+ G -Scalar	
- 18	
- 18	
- 18	
3 + 12+ 2 - 18 =	-1
2 + 14+ 4 - 18 =	+2
5 + 8 + 8 - 18 =	+3
1 + 16+ 2 - 18 =	+1
0 + 18+ 0 - 18 =	0

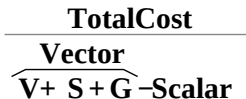
TSLP

Cost calculation example



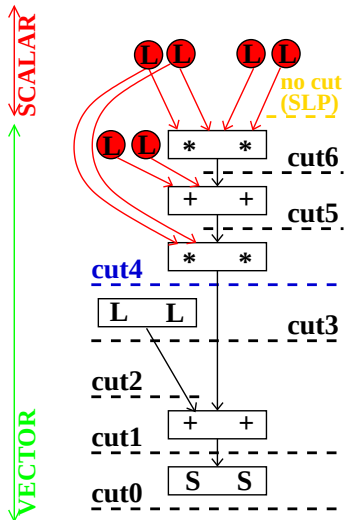
TotalCost	
Vector	
V+ S+ G -Scalar	
- 18	
- 18	
4 + 10+ 4 - 18 =	0
3 + 12+ 2 - 18 =	-1
2 + 14+ 4 - 18 =	+2
5 + 8 + 8 - 18 =	+3
1 + 16+ 2 - 18 =	+1
0 + 18+ 0 - 18 =	0

TSLP



TSLP

Cost calculation example

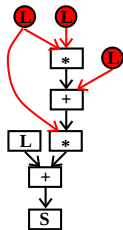


TotalCost		
Vector		
V	S + G	-Scalar
6 + 6 + 6	- 18	= 0
5 + 8 + 6	- 18	= +1
4 + 10 + 4	- 18	= 0
3 + 12 + 2	- 18	= -1
2 + 14 + 4	- 18	= +2
5 + 8 + 8	- 18	= +3
1 + 16 + 2	- 18	= +1
0 + 18 + 0	- 18	= 0

SLP

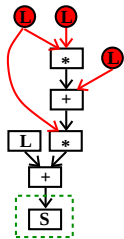
TSLP

Subgraph (Cuts) Generation Algorithm



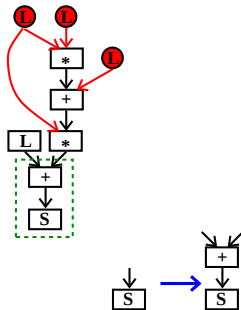
- Only connected subgraphs that include the root

Subgraph (Cuts) Generation Algorithm



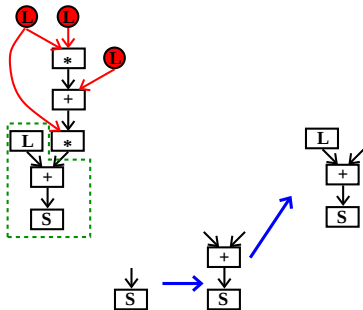
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Subgraph (Cuts) Generation Algorithm



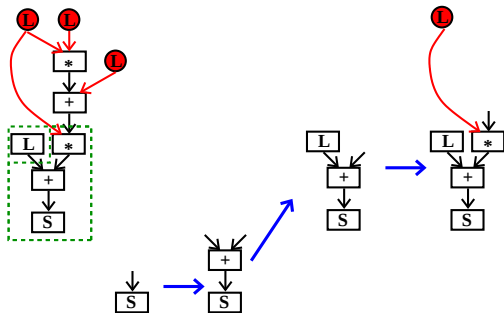
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Subgraph (Cuts) Generation Algorithm



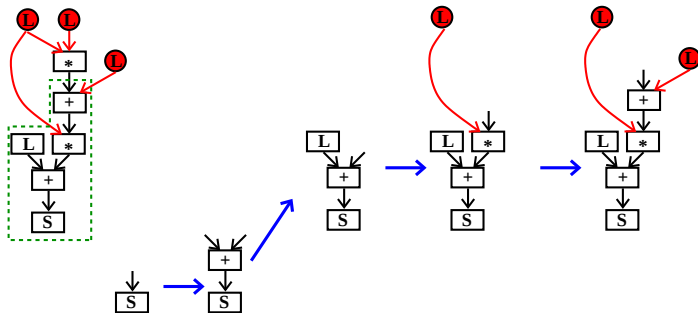
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Subgraph (Cuts) Generation Algorithm



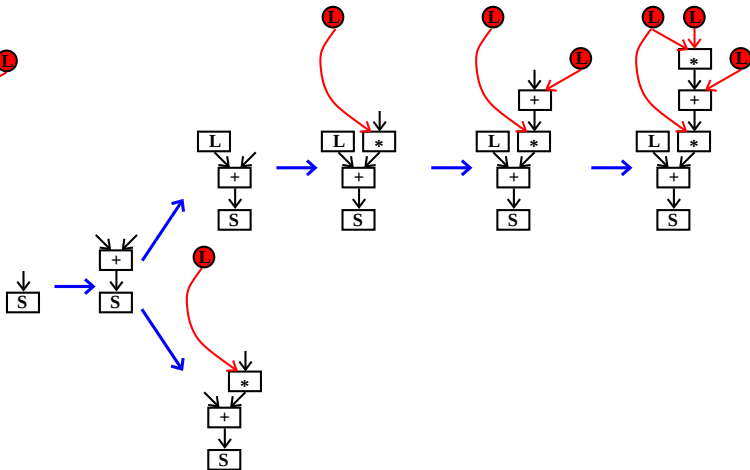
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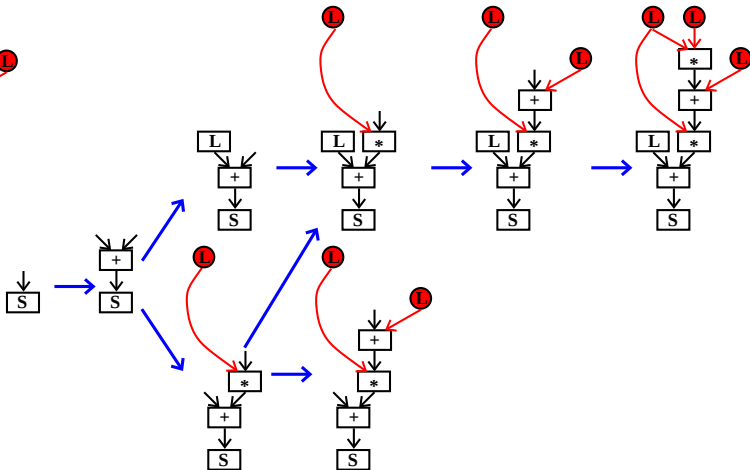
- Only connected subgraphs that include the root

Subgraph (Cuts) Generation Algorithm



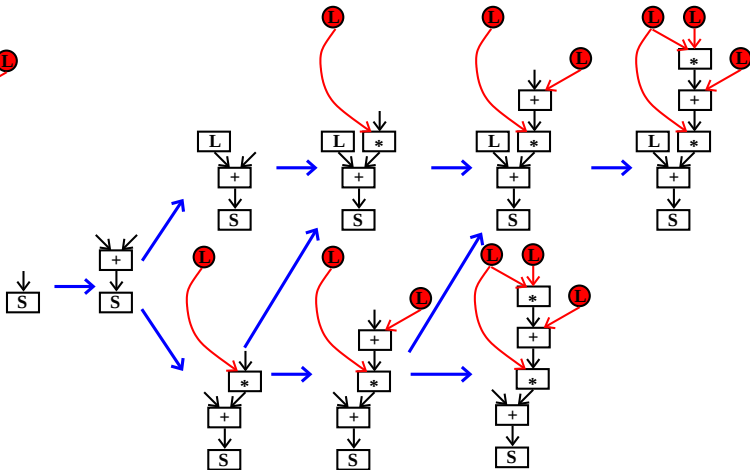
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Subgraph (Cuts) Generation Algorithm



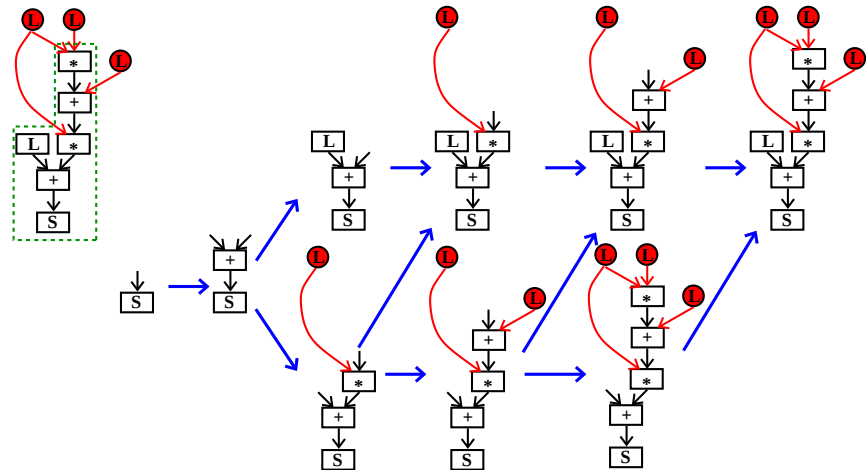
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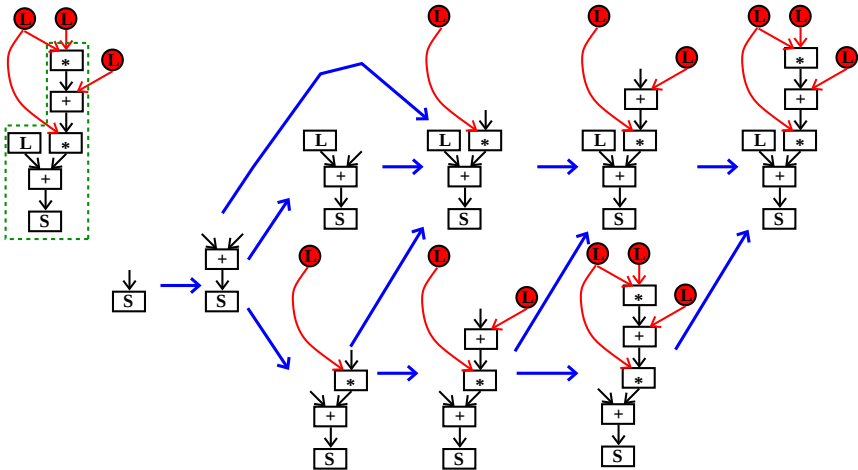
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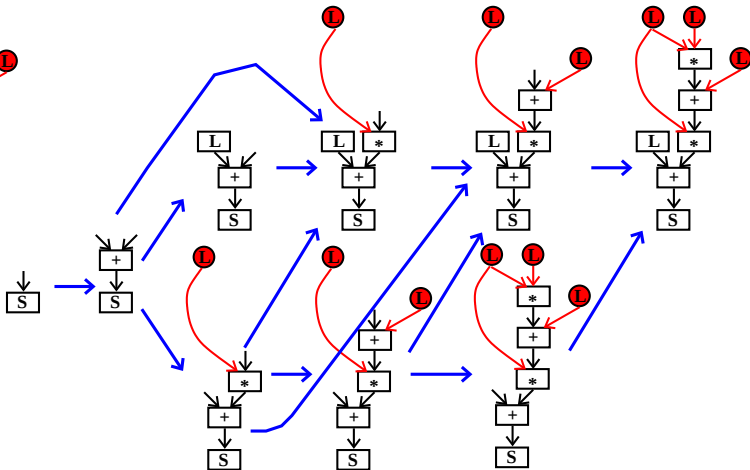
- Only connected subgraphs that include the root

Subgraph (Cuts) Generation Algorithm



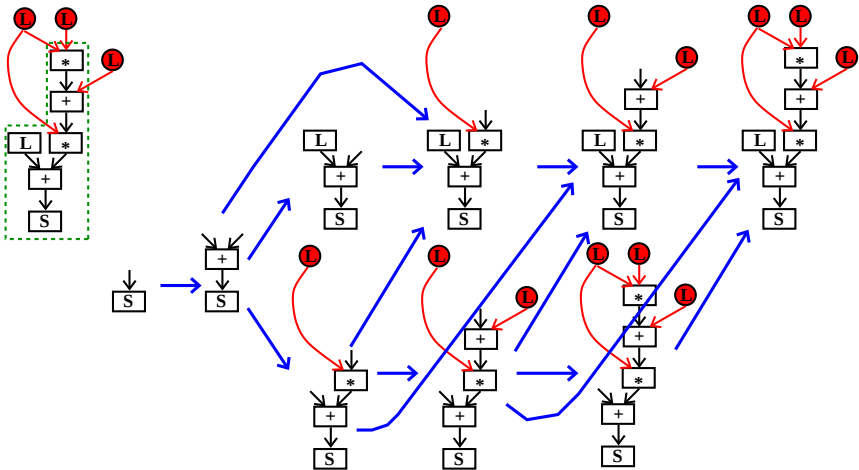
- Only connected subgraphs that include the root

Subgraph (Cuts) Generation Algorithm



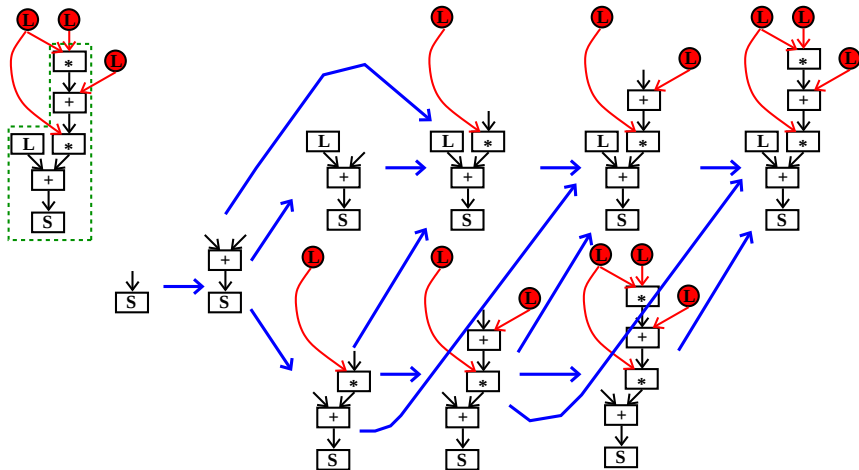
- Only connected subgraphs that include the root

Subgraph (Cuts) Generation Algorithm



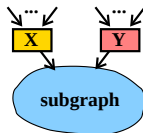
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Subgraph (Cuts) Generation Algorithm

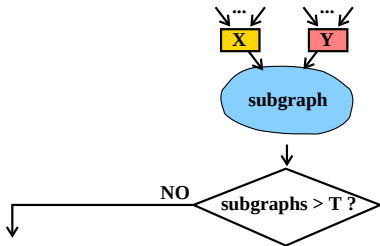


- Only connected subgraphs that include the root
- Worst time complexity $O(2^B \times N)$ (N =Nodes, B =Neighbors)

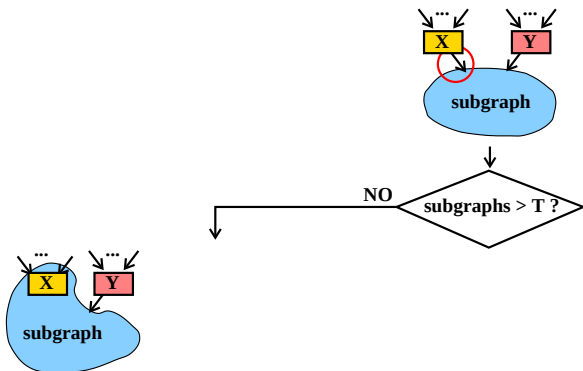
Fast Subgraph (Cuts) Generation Algorithm



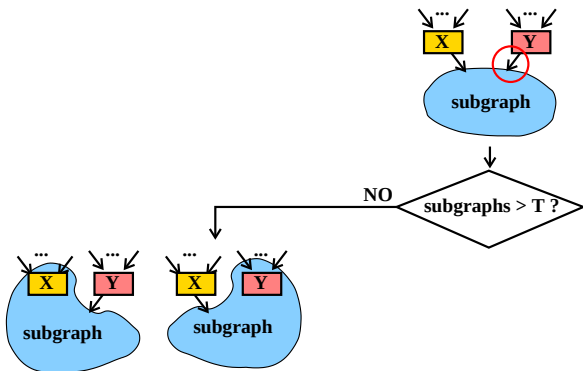
Fast Subgraph (Cuts) Generation Algorithm



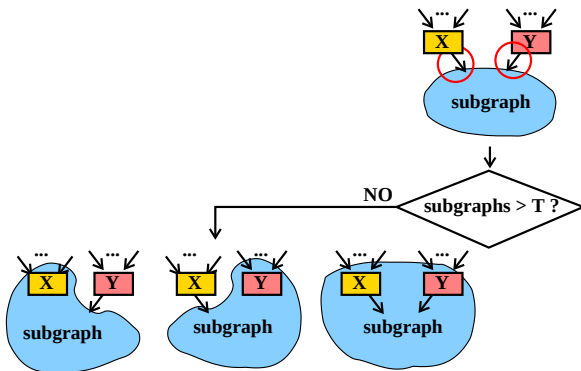
Fast Subgraph (Cuts) Generation Algorithm



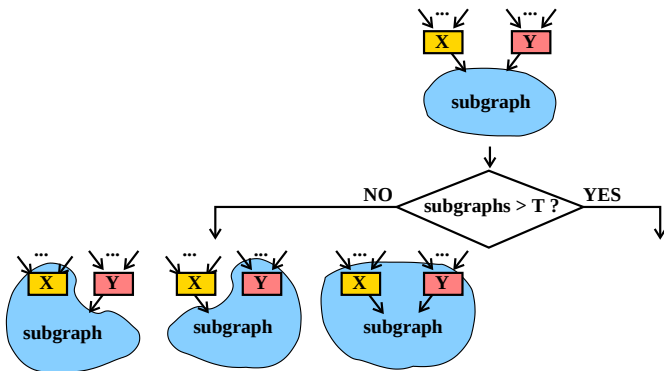
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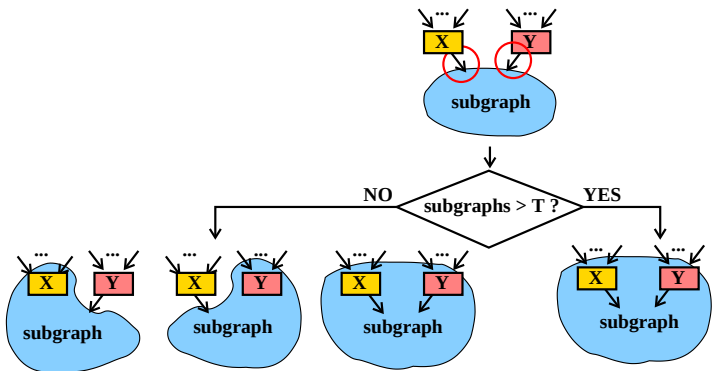


Fast Subgraph (Cuts) Generation Algorithm



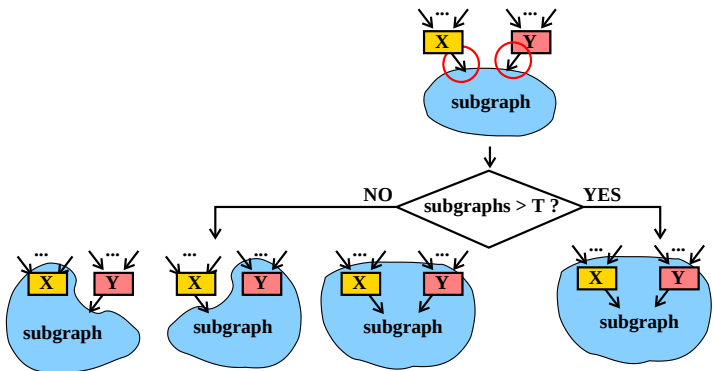
- After T subgraphs, attach all neighbors

Fast Subgraph (Cuts) Generation Algorithm



- After T subgraphs, attach all neighbors

Fast Subgraph (Cuts) Generation Algorithm



- After T subgraphs, attach all neighbors
- Complexity reduced to linear $O(T + N)$

Experimental Setup

- Implemented TSLP in the trunk version of the LLVM 3.6 compiler.

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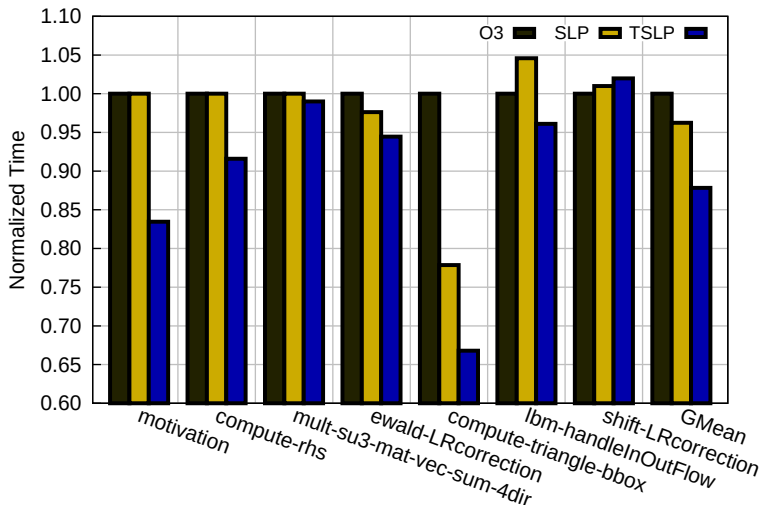
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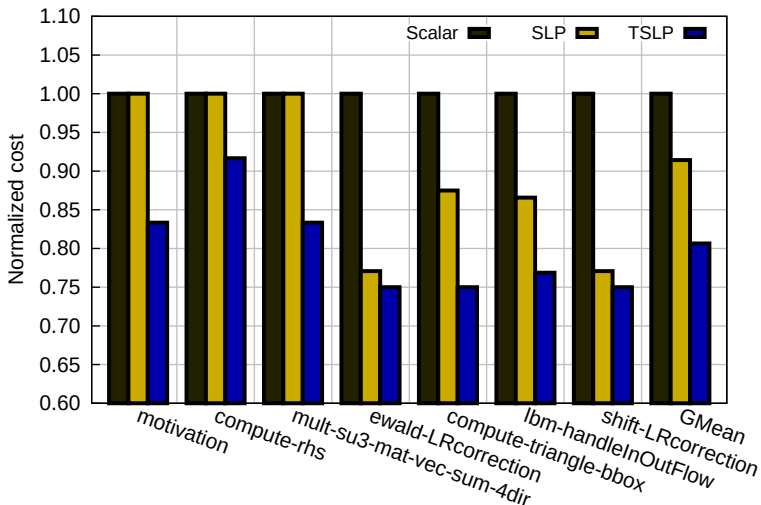
TSLP increases performance

Performance

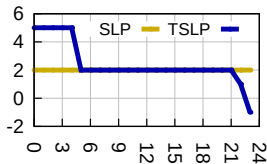


TSLP static cost savings

Avg. static Scalar, SLP and TSLP cost normalized to Scalar



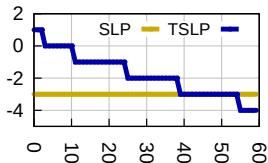
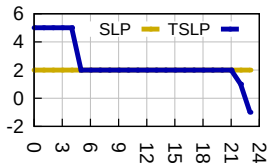
TSLP TotalCost exploration



mult-su3-mat-vec-sum

- SLP non-profitable, TSLP profitable

TSLP TotalCost exploration

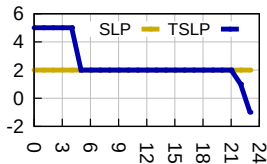


mult-su3-mat-vec-sum

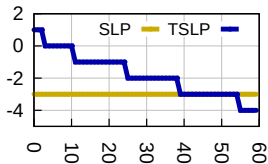
lbm-handleInOutFlow-3

- SLP non-profitable, TSLP profitable
- SLP profitable, but TSLP more profitable

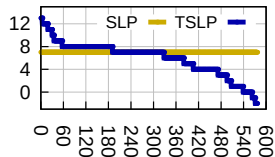
TSLP TotalCost exploration



mult-su3-mat-vec-sum



lbm-handleInOutFlow-3



lab-handleInOutFlow-5

- SLP non-profitable, TSLP profitable
- SLP profitable, but TSLP more profitable
- TSLP exploration gradually improves cost

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- Removes non-profitable code regions by:
 - Evaluating a number of possible cuts
 - Estimating their cost
 - Applying the cut with the minimal cost
- TSLP performs better compared to SLP on commodity SIMD-capable hardware